


HW 11 due tonight!

- I'm going to grade it Fri @ 3pm

Feel free to upload it before then.

Last time ...

$$e^A = I + A + \frac{1}{2} A^2 + \frac{1}{3!} A^3 + \dots$$

$$= \sum_{n=0}^{\infty} \frac{1}{n!} A^n$$

But what is A explicitly? How do you calculate it?

e^{At} sol'n to

$$\vec{v}'(t) = A \vec{v}(t)$$

$$\Rightarrow \vec{v}(t) = e^{At} \vec{v}(0)$$

What is e^A ?

Prop

- e^A respects change of basis.

If $A = SJS^{-1}$ then

$$\underline{e^A = Se^J S^{-1}}$$

- If $D = \begin{pmatrix} d_1 & & \\ & \ddots & \\ & & d_n \end{pmatrix}$

then $e^D = \begin{pmatrix} e^{d_1} & & 0 \\ & e^{d_2} & \\ 0 & & \ddots \\ & & & e^{d_n} \end{pmatrix}$

- If $AB = BA$ then

$$e^B e^A = e^{A+B} = e^A e^B$$

$$e^{x+y} = e^x e^y$$

Quick Pf

$$e^A = \sum \frac{1}{n!} A^n = \sum \frac{1}{n!} (S J S^{-1})^n$$

$$(S J S^{-1})^3 = S J S^{-1} \cancel{S J S^{-1}} \cancel{S J S^{-1}} S J S^{-1} = S J^3 S^{-1}$$

$$= \sum \frac{1}{n!} S J^n S^{-1} = S \left(\sum \frac{1}{n!} J^n \right) S^{-1}$$

$$= S e^J S^{-1}$$

$$e^D = \sum \frac{1}{n!} \begin{pmatrix} d_1 & & \\ & \ddots & \\ & & d_k \end{pmatrix}^n = \sum \frac{1}{n!} \begin{pmatrix} d_1^n & & \\ & \ddots & \\ & & d_k^n \end{pmatrix}$$

$$= \begin{pmatrix} \sum \frac{1}{n!} d_1^n & & \\ & \ddots & \\ & & \sum \frac{1}{n!} d_k^n \end{pmatrix} = \begin{pmatrix} e^{d_1} & & \\ & e^{d_2} & \\ & & \ddots \\ & & & e^{d_k} \end{pmatrix}$$

• If $AB = BA$

$$e^{A+B} = I + (A+B) + \frac{1}{2}(A+B)^2 + \frac{1}{3!}(A+B)^3 + \dots$$

$$\underbrace{\frac{1}{2}(A+B)^2}_{\text{if } AB \neq BA \text{ then this is the best you can simplify}} = \frac{1}{2}(A^2 + AB + BA + B^2)$$

$$= \frac{1}{2}(A^2 + 2AB + B^2)$$

$$e^{A+B} = I + (A+B) + \frac{1}{2}(A^2 + 2AB + B^2) + \frac{1}{3!}(A^3 + 3A^2B + 3AB^2 + B^3) + \dots$$

really depends

$$= \left(I + A + \frac{1}{2}A^2 + \frac{1}{3!}A^3 + \dots \right) \left(I + B + \frac{1}{2}B^2 + \frac{1}{3!}B^3 + \dots \right) \overset{\text{or}}{AB = BA}$$

$$= e^A e^B$$

□

Ex Compute $e^{\begin{pmatrix} 1 & -1 \\ 1 & 3 \end{pmatrix}}$.

Step 1 Find the Jordan decomposition $\approx \begin{pmatrix} 1 & -1 \\ 1 & 3 \end{pmatrix}$.

$$\begin{pmatrix} 1 & -1 \\ 1 & 3 \end{pmatrix} = \begin{pmatrix} -1 & 2 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 2 & 1 \\ 0 & 2 \end{pmatrix} \begin{pmatrix} -1 & 2 \\ 1 & -1 \end{pmatrix}^{-1}$$

↑
generalized
eigenvector

$$e^{SJS^{-1}} = Se^J S^{-1}$$

$$e^{\begin{pmatrix} 1 & -1 \\ 1 & 3 \end{pmatrix}} = \begin{pmatrix} -1 & 2 \\ 1 & -1 \end{pmatrix} e^{\begin{pmatrix} 2 & 1 \\ 0 & 2 \end{pmatrix}} \begin{pmatrix} -1 & 2 \\ 1 & -1 \end{pmatrix}^{-1}$$

Simple
to compute

matrix J all
the 1's

Step 2

$$e^{\begin{pmatrix} 2 & 1 \\ 0 & 2 \end{pmatrix}} = e^{\begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix}} + e^{\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}}$$

$$e^{A+B} = e^A e^B$$

$$AB = BA$$

In fact $\begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix}$

turns out
 Δ, N always
 commute
 when $J = \Delta + N$

$$e^{\begin{pmatrix} 2 & 1 \\ 0 & 2 \end{pmatrix}} = e^{\begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix}} e^{\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}}$$

Step 3

$$e^{\begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix}} = \begin{pmatrix} e^2 & 0 \\ 0 & e^2 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}^2 = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

(nilpotent matrix)

$$e^D = \begin{pmatrix} e^{\lambda_1} & & \\ & \ddots & \\ & & e^{\lambda_n} \end{pmatrix}$$

$$e^{\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}} = I + \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} + \frac{1}{2} \cancel{\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}^2} + \frac{1}{3!} \cancel{\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}^3} + \dots \cancel{\dots}$$

$N^k = 0$

$$e^{\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} + \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$$

Step 4 Put it all together!

$$\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}^2 = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

$$e^{\begin{pmatrix} 1 & -1 \\ 1 & 3 \end{pmatrix}} = \begin{pmatrix} -1 & 2 \\ 1 & -1 \end{pmatrix} e^{\begin{pmatrix} 2 & 1 \\ 0 & 2 \end{pmatrix}} \begin{pmatrix} -1 & 2 \\ 1 & -1 \end{pmatrix}^{-1}$$

$$= \begin{pmatrix} -1 & 2 \\ 1 & -1 \end{pmatrix} e^{\begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix}} e^{\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}} \begin{pmatrix} -1 & 2 \\ 1 & -1 \end{pmatrix}^{-1}$$

Step 2

$$= \begin{pmatrix} -1 & 2 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} e^2 & 0 \\ 0 & e^2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \frac{1}{-1} \begin{pmatrix} -1 & -2 \\ -1 & -1 \end{pmatrix}$$

$$= \begin{pmatrix} -1 & 2 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} e^2 & e^2 \\ 0 & e^2 \end{pmatrix} \begin{pmatrix} 1 & -2 \\ 1 & 1 \end{pmatrix}$$

$$e^{\begin{pmatrix} 1 & -1 \\ 1 & 3 \end{pmatrix}} = \begin{pmatrix} 0 & -e^2 \\ e^2 & 2e^2 \end{pmatrix}$$

Idea: These steps work for all matrices.

Ex $e^{\begin{pmatrix} 7 & 8 \\ -4 & -5 \end{pmatrix}}$

Step 1 $\begin{pmatrix} 7 & 8 \\ -4 & -5 \end{pmatrix} = \begin{pmatrix} -1 & 2 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} -1 & 0 \\ 0 & 3 \end{pmatrix} \begin{pmatrix} -1 & 2 \\ 1 & -1 \end{pmatrix}^{-1}$

$e^{\begin{pmatrix} 7 & 8 \\ -4 & -5 \end{pmatrix}} = \begin{pmatrix} -1 & 2 \\ 1 & -1 \end{pmatrix} e^{\begin{pmatrix} -1 & 0 \\ 0 & 3 \end{pmatrix}} \begin{pmatrix} -1 & 2 \\ 1 & -1 \end{pmatrix}^{-1}$

Step 2, Step 3

$= \begin{pmatrix} -1 & 2 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} e^{-1} & 0 \\ 0 & e^3 \end{pmatrix} \begin{pmatrix} -1 & 2 \\ 1 & -1 \end{pmatrix}^{-1}$

$e^{\begin{pmatrix} 7 & 8 \\ -4 & -5 \end{pmatrix}} = \begin{pmatrix} 2e^3 - e^{-1} & 2e^3 - 2e^{-1} \\ -e^3 + e^{-1} & -e^3 + 2e^{-1} \end{pmatrix}$

Ex

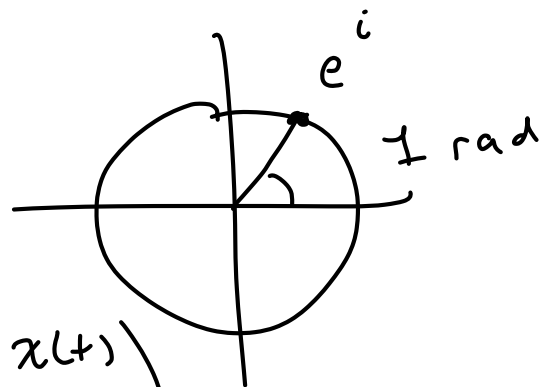
$$e^{\begin{pmatrix} 0 & 0 & 0 \\ 0 & -i & 0 \\ 0 & 0 & i \end{pmatrix}} = \begin{pmatrix} e^0 & 0 & 0 \\ 0 & e^{-i} & 0 \\ 0 & 0 & e^i \end{pmatrix}$$

$$e^{ix} = \cos(x) + i \sin(x)$$

$x = \theta$ angle

$$e^{i\frac{\pi}{2}} = \cos\left(\frac{\pi}{2}\right) + i \sin\left(\frac{\pi}{2}\right) = i$$

$$x = 1, \quad e^i = \cos(1) + i \sin(1)$$



$$\frac{dx}{dt} = -y$$

$$\frac{dy}{dt} = x$$

$$\Rightarrow \begin{pmatrix} x'(t) \\ y'(t) \end{pmatrix} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} x(t) \\ y(t) \end{pmatrix}$$

$$\begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = e^{\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} t} \begin{pmatrix} x(0) \\ y(0) \end{pmatrix}$$

Ex

$$e^{\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} t}$$

$$\det \begin{pmatrix} 0-\lambda & -1 \\ 1 & 0-\lambda \end{pmatrix} = 0$$

$$\lambda^2 + 1 = 0$$

$$\lambda = \pm i$$

$$V_i \subseteq \mathbb{C}^2$$

$$V_i = \ker(A - iI) = \ker \begin{pmatrix} -i & -1 \\ 1 & -i \end{pmatrix}$$

$$\begin{pmatrix} -i & -1 \\ 1 & -i \end{pmatrix} \rightarrow \begin{pmatrix} 1 & -i \\ -i & 1 \end{pmatrix}$$

$$\xrightarrow{i r_1 + r_2} \begin{pmatrix} 1 & -i \\ 0 & 0 \end{pmatrix}$$

RREF

$$x = iy \quad y \text{ free}$$

$$V_i = \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} iy \\ y \end{pmatrix} = \begin{pmatrix} i \\ 1 \end{pmatrix} y \quad v = \begin{pmatrix} i \\ 1 \end{pmatrix}$$

$$V_{-i} = \text{span} \begin{pmatrix} -i \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} = \begin{pmatrix} i & -i \\ 1 & 1 \end{pmatrix} \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix} \begin{pmatrix} i & -i \\ 1 & 1 \end{pmatrix}^{-1}$$

$$e^{\begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}} = \begin{pmatrix} i & -i \\ 1 & 1 \end{pmatrix} e^{\begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix}} \frac{1}{\det \begin{pmatrix} 1 & i \\ -1 & i \end{pmatrix}}$$

$$= \begin{pmatrix} i & -i \\ 1 & 1 \end{pmatrix} \begin{pmatrix} e^i & 0 \\ 0 & e^{-i} \end{pmatrix} \frac{1}{2i} \begin{pmatrix} 1 & i \\ -1 & i \end{pmatrix}$$

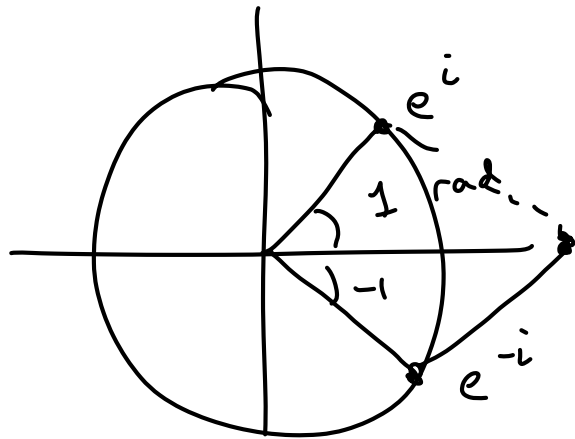
$$= \frac{1}{2i} \begin{pmatrix} i & -i \\ 1 & 1 \end{pmatrix} \begin{pmatrix} e^i & 0 \\ 0 & e^{-i} \end{pmatrix} \begin{pmatrix} 1 & i \\ -1 & i \end{pmatrix}$$

$$= \frac{1}{2i} \begin{pmatrix} ie^i & -ie^{-i} \\ e^i & e^{-i} \end{pmatrix} \begin{pmatrix} 1 & i \\ -1 & i \end{pmatrix}$$

$$= \frac{1}{2i} \begin{pmatrix} ie^i + ie^{-i} & -e^i + e^{-i} \\ e^i - e^{-i} & ie^i + ie^{-i} \end{pmatrix}$$

you
can stop
on HW

10.4.2a



$$e^i, e^{-i}$$

$$e^i + e^{-i} = 2\cos(1)$$

$$e^i = \cos(1) + i\sin(1)$$

$$e^{-i} = \cos(-1) + i\sin(-1) = \cos(1) - i\sin(1)$$

So $e^{\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}}$ will be real if you keep simplifying

$$e^{\begin{pmatrix} -1 & 5 & -3 \\ -2 & -5 & 1 \\ -3 & -1 & -1 \end{pmatrix}}$$

$$\begin{pmatrix} -1 & 5 & -3 \\ -2 & -5 & 1 \\ -3 & -1 & -1 \end{pmatrix} = \begin{pmatrix} -1 & -\frac{1}{2} & -1 \\ 0 & \frac{1}{2} & 1 \\ -1 & 0 & 2 \end{pmatrix} \begin{pmatrix} -2 & 1 \\ -2 & 2 \\ \dots \end{pmatrix}^{-1}$$

↑
↑
generalized
eigenvector

$$= \begin{pmatrix} -1 & -\frac{1}{2} & -1 \\ 0 & \frac{1}{2} & 1 \\ -1 & 0 & 2 \end{pmatrix} e^{\begin{pmatrix} -2 & 1 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & 2 \end{pmatrix}} \begin{pmatrix} -1 & -\frac{1}{2} & -1 \\ 0 & \frac{1}{2} & 1 \\ -1 & 0 & 2 \end{pmatrix}^{-1}$$

$$\begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}^2 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$= \begin{pmatrix} -1 & -\frac{1}{2} & -1 \\ 0 & \frac{1}{2} & 1 \\ -1 & 0 & 2 \end{pmatrix} e^{\begin{pmatrix} -2 & 1 & 0 \\ -2 & -2 & 0 \\ 2 & 0 & 2 \end{pmatrix}} e^{\begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}} \begin{pmatrix} -1 & -\frac{1}{2} & -1 \\ 0 & \frac{1}{2} & 1 \\ -1 & 0 & 2 \end{pmatrix}$$

$$S \begin{pmatrix} e^{-2} & & \\ & e^{-2} & \\ & & e^2 \end{pmatrix} e^{\begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}} S^{-1} = \dots$$

$$e^{2N} = I + N$$

HW 11 due tonight (Fri 3pm)

Office hrs tomorrow 12/17 usual time 12-3

Office hrs Friday 12/18 12-3

Final Monday 12/21 1:30 - 3:30

$$\begin{pmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\begin{aligned} x + z &= 0 \\ y &= -1 \end{aligned}$$

7 free

$$\begin{pmatrix} 1 & -1 & z \end{pmatrix}$$

$$w_2 = \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -z \\ -1 \\ z \end{pmatrix}$$

$$= \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} z + \begin{pmatrix} 0 \\ -1 \\ 0 \end{pmatrix}$$

$\ker(A) +$ particular solution

$$\underline{Ax=b}$$

$$w_2 = \begin{pmatrix} 0 \\ -1 \\ 0 \end{pmatrix}$$