


$$1. \text{ let } A = \begin{pmatrix} 2 & 3 & -2 \\ -3 & 0 & 0 \\ -4 & -6 & 4 \end{pmatrix}.$$

$$a) \det(A - \lambda I) = 0$$

$$\det \begin{pmatrix} 2 - \lambda & 3 & -2 \\ -3 & -\lambda & 0 \\ -4 & -6 & 4 - \lambda \end{pmatrix} = 0$$

$$3 \det \begin{pmatrix} 3 & -2 \\ -6 & 4 - \lambda \end{pmatrix} + (-\lambda) \det \begin{pmatrix} 2 - \lambda & -2 \\ -4 & 4 - \lambda \end{pmatrix} = 0$$

$$3(3(4 - \lambda) - 12) + (-\lambda)((2 - \lambda)(4 - \lambda) - 8) = 0$$

$$3(\cancel{12} - 3\lambda - \cancel{12}) + -\lambda(8 - 6\lambda^2 + \lambda^2 - 8) = 0$$

$$-9\lambda + -\lambda(\lambda^2 - 6\lambda) = 0$$

$$-\lambda^3 + 6\lambda^2 - 9\lambda = 0$$

$$-\lambda(\lambda^2 - 6\lambda + 9) = 0$$

$$-\lambda(\lambda - 3)^2 = 0$$

$$\boxed{\lambda = 0}, \quad \boxed{\lambda = 3, 3}$$

$$(b) \quad V_0 = \ker(A - 0I) = \ker(A)$$

$$= \ker \begin{pmatrix} 2 & 3 & -2 \\ -3 & 0 & 0 \\ -4 & -6 & 4 \end{pmatrix}$$

$$\begin{pmatrix} 2 & 3 & -2 \\ -3 & 0 & 0 \\ -4 & -6 & 4 \end{pmatrix} \xrightarrow{2r_1 + r_3} \begin{pmatrix} 2 & 3 & 2 \\ -3 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\xrightarrow{\frac{3}{2}r_1 + r_2} \begin{pmatrix} 2 & 3 & 2 \\ 0 & 9/2 & 3 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\xrightarrow{-\frac{2}{3}r_2 + r_1} \begin{pmatrix} 2 & 0 & 0 \\ 0 & 9/2 & 3 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\xrightarrow{\quad} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & -2/3 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\text{So } \ker(A) = \begin{pmatrix} 0 \\ 2/3 z \\ z \end{pmatrix} = \text{Span} \left(\begin{pmatrix} 0 \\ 2 \\ 3 \end{pmatrix} \right)$$

So the eigenvalue $\lambda = 0$ has alg mult = 1
and geom mult = 1

$$V_{\lambda=3} = \ker(A - 3I) = \ker \begin{pmatrix} -1 & 3 & -2 \\ -3 & -3 & 0 \\ -4 & -6 & 1 \end{pmatrix}$$

$$\begin{pmatrix} -1 & 3 & -2 \\ -3 & -3 & 0 \\ -4 & -6 & 1 \end{pmatrix} \xrightarrow{-r_1 - r_2 - r_3} \begin{pmatrix} 1 & -3 & 2 \\ 3 & 3 & 0 \\ 4 & 6 & -1 \end{pmatrix}$$

$$\xrightarrow{\substack{-3r_1 + r_2 \\ r_4r_1 + r_3}} \begin{pmatrix} 1 & -3 & 2 \\ 0 & 12 & -6 \\ 0 & 18 & -9 \end{pmatrix}$$

$$\begin{array}{l} -3/2 r_2 + r_3 \\ \longrightarrow \\ \frac{1}{6} r_2 \end{array} \begin{pmatrix} 1 & -3 & 2 \\ 0 & 2 & -1 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\begin{array}{l} \frac{3}{2} r_2 + r_1 \\ \longrightarrow \end{array} \begin{pmatrix} 1 & 0 & 1/2 \\ 0 & 2 & -1 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\begin{array}{l} \frac{1}{2} r_2 \\ \longrightarrow \end{array} \begin{pmatrix} 1 & 0 & 1/2 \\ 0 & 1 & -1/2 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\begin{aligned} \text{So } V_3 &= \ker(A - 3I) = \begin{pmatrix} -1/2 & 2 \\ 1/2 & 2 \\ & 2 \end{pmatrix} \\ &= \text{span} \left(\begin{pmatrix} -1 \\ 1 \\ 2 \end{pmatrix} \right) \end{aligned}$$

So the alg mult of $\lambda = 3$ is 2
but the geom mult is 1.

(c) We need 1 generalized eigenvector for $\lambda = 3$. Therefore we solve

$$(A - 3I)w_2 = \begin{pmatrix} -1 \\ 1 \\ 2 \end{pmatrix}$$

$$\begin{pmatrix} -1 & 3 & -2 \\ -3 & -3 & 0 \\ -4 & -6 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -1 \\ 1 \\ 2 \end{pmatrix}$$

$$\begin{pmatrix} -1 & 3 & -2 & \vdots & -1 \\ -3 & -3 & 0 & \vdots & 1 \\ -4 & -6 & 1 & \vdots & 2 \end{pmatrix} \quad \text{Same steps!}$$

$$\begin{pmatrix} -1 \\ 1 \\ 2 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 \\ -1 \\ -2 \end{pmatrix} \xrightarrow{\substack{-3r_1 + r_2 \\ -4r_1 + r_3}} \begin{pmatrix} 1 \\ -4 \\ -6 \end{pmatrix}$$

$$\begin{array}{l} -\frac{3}{2}r_2 + r_3 \\ \xrightarrow{\frac{1}{6}r_2} \end{array} \begin{pmatrix} 1 \\ -2/3 \\ 0 \end{pmatrix} \xrightarrow{\frac{3}{2}r_2 + r_1} \begin{pmatrix} 0 \\ -2/3 \\ 0 \end{pmatrix}$$

$$\xrightarrow{\frac{1}{2}r_2} \begin{pmatrix} 0 \\ -1/3 \\ 0 \end{pmatrix} \quad \text{so}$$

RREF

$$\Rightarrow \begin{pmatrix} 1 & 0 & 1/2 & \vdots & 0 \\ 0 & 1 & -1/2 & \vdots & -1/3 \\ 0 & 0 & 0 & \vdots & 0 \end{pmatrix} \quad \text{and}$$

$$w_2 = \begin{pmatrix} -1 \\ 1 \\ 2 \end{pmatrix} z + \begin{pmatrix} 0 \\ -1/3 \\ 0 \end{pmatrix} \quad \text{and we can}$$

use $\begin{pmatrix} 0 \\ -1/3 \\ 0 \end{pmatrix}$ as the generalized eigenvector.

Therefore the Jordan decomposition is

$$A = \begin{pmatrix} 0 & -1 & 0 \\ 2 & 1 & -1/3 \\ 3 & 2 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 & 0 \\ 0 & 3 & 1 \\ 0 & 0 & 3 \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ 2 & 1 & -1/3 \\ 3 & 2 & 0 \end{pmatrix}^{-1}$$

2. In matrix form this system is

$$\begin{pmatrix} 2 & 3 \\ -1 & -1 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 2 \\ 0 \end{pmatrix}$$

Therefore the LSS is

$$x^* = (A^T A)^{-1} A^T b$$

$$\bullet \quad A^T A = \begin{pmatrix} 2 & -1 & 2 \\ 3 & -1 & 1 \end{pmatrix} \begin{pmatrix} 2 & 3 \\ -1 & -1 \\ 2 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} 9 & 9 \\ 9 & 11 \end{pmatrix}$$

$$(A^T A)^{-1} = \frac{1}{18} \begin{pmatrix} 11 & -9 \\ -9 & 9 \end{pmatrix}$$

$$\bullet \quad A^T b = \begin{pmatrix} 2 & -1 & 2 \\ 3 & -1 & 1 \end{pmatrix} \begin{pmatrix} 0 \\ 2 \\ 0 \end{pmatrix} = \begin{pmatrix} -2 \\ -2 \end{pmatrix}$$

So the LSS explicitly is

$$x^* = \frac{1}{18} \begin{pmatrix} 11 & -9 \\ -9 & 9 \end{pmatrix} \begin{pmatrix} -2 \\ -2 \end{pmatrix} = \boxed{\frac{1}{18} \begin{pmatrix} -4 \\ 0 \end{pmatrix}}$$

3.

(a) The vertex-edge formula says that

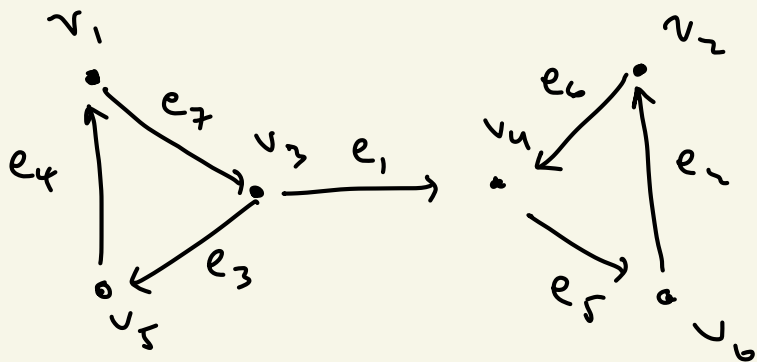
$$\#v - \#e = 1 - \# \text{ ind circ}$$

$$\text{So } 6 - 7 = 1 - \# \text{ ind circ}$$

$$\Rightarrow \boxed{\# \text{ ind circ} = 2}$$

This is expected since the graph has 2 "holes" in it. One given by $e_3 + e_4 + e_7$ and the other $e_2 + e_5 + e_6$.

(b) $\partial(e) = \text{end} - \text{start}$, so we need to label the vertices first.



And a circuit is an element of the kernel of ∂

$$\begin{aligned} \partial(e_1 + e_2 - 2e_3 - 2e_4 + e_5 + e_6 - 2e_7) \\ = v_4 - v_3 + \cancel{v_2} - \cancel{v_6} - 2\cancel{v_5} + \cancel{2v_3} - \cancel{2v_1} + \cancel{2v_5} \\ + \cancel{v_6} - \cancel{v_4} + \cancel{v_4} - \cancel{v_2} - 2\cancel{v_3} + \cancel{2v_1} \end{aligned}$$

$$= v_4 - v_3 \neq 0. \quad \text{So this is not a circuit.}$$

4.

(a) Writing $\langle -, - \rangle$ in matrix form we have

$$\begin{aligned} & \langle (x_1, y_1), (x_2, y_2) \rangle \\ &= (x_1, y_1) \begin{pmatrix} 2 & -1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} x_2 \\ y_2 \end{pmatrix} \end{aligned}$$

Bilinearity

$$\cdot \langle \vec{u} + \vec{v}, \vec{w} \rangle = (\vec{u} + \vec{v})^T \begin{pmatrix} 2 & -1 \\ -1 & 1 \end{pmatrix} \vec{w}$$

$$= (\vec{u}^T + \vec{v}^T) \begin{pmatrix} 2 & -1 \\ -1 & 1 \end{pmatrix} \vec{w}$$

$$= \vec{u}^T \begin{pmatrix} 2 & -1 \\ -1 & 1 \end{pmatrix} \vec{w} + \vec{v}^T \begin{pmatrix} 2 & -1 \\ -1 & 1 \end{pmatrix} \vec{w}$$

$$= \langle \vec{u}, \vec{w} \rangle + \langle \vec{v}, \vec{w} \rangle$$

$$\cdot \langle c\vec{v}, \vec{w} \rangle = (c\vec{v})^T \begin{pmatrix} 2 & -1 \\ -1 & 1 \end{pmatrix} \vec{w}$$

$$= c \vec{v}^T \begin{pmatrix} 2 & -1 \\ -1 & 1 \end{pmatrix} \vec{w} = c \langle \vec{v}, \vec{w} \rangle$$

The other side is similar. ✓

Symmetry

$$\langle \vec{x}_1, \vec{x}_2 \rangle = 2x_1x_2 - x_1y_2 - x_2y_1 + y_1y_2$$

$$= 2x_2x_1 - x_2y_1 - x_1y_2 + y_2y_1$$

$$= \langle \vec{x}_2, \vec{x}_1 \rangle. \quad \checkmark$$

Positivity.

Recall that $v^T K v > 0$ for all $v \neq 0$
iff K is positive definite.

But K is positive definite since

$$\det \begin{pmatrix} 2-\lambda & -1 \\ -1 & 1-\lambda \end{pmatrix} = 0$$

$$(2-\lambda)(1-\lambda) - 1 = 0$$

$$\lambda^2 - 3\lambda + 2 - 1 = 0$$

$$\lambda^2 - 3\lambda + 1 = 0$$

$$\lambda = \frac{3 \pm \sqrt{9-4}}{2} = \frac{3 \pm \sqrt{5}}{2} > 0$$

Let's eigenvalues are both positive!

$$\text{So } \langle v, v \rangle = v^T \begin{pmatrix} 2 & -1 \\ -1 & 1 \end{pmatrix} v > 0$$

and $\langle -, - \rangle$ is positive. ✓

$$(b) \quad |2v_1v_2 - v_1w_2 - v_2w_1 + w_1w_2|$$

$$\leq \sqrt{2v_1^2 - 2v_1v_2 + v_2^2} \sqrt{2w_1^2 - 2w_1w_2 + w_2^2}$$

5.

(a) The vectors $\{v_1, v_2, v_3, v_4\}$ do not form a basis of any \mathbb{R}^n . These vectors live in \mathbb{R}^4 so the only possibility is $n=4$. But they don't form a basis of \mathbb{R}^4 either.

They are not independent since $v_3 \in \text{span}(v_1, v_2)$ according to the RREF. In particular

$$v_3 = -2v_1 + 4v_2 \text{ is a dependency.}$$

They also don't span since $\begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} \notin \text{span}$ of columns of RREF.

Since they neither span nor are independent, they can't be a basis.

$$(b) \ker(M) = \ker \begin{pmatrix} 1 & 0 & -2 & 0 \\ 0 & 1 & 4 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix} \quad \begin{array}{l} x = 2z \\ y = -4z \\ w = 0 \end{array}$$

$$\ker(M) = \begin{pmatrix} 2z \\ -4z \\ z \\ 0 \end{pmatrix} = \text{span} \begin{pmatrix} 2 \\ -4 \\ 1 \\ 0 \end{pmatrix}$$

$$\text{Thus } \dim(\ker(M)) = 1.$$

(c). By rank-nullity

$$\dim(\ker(M)) + \text{rank}(M) = 4$$

$$1 + \text{rank}(M) = 4$$

$$\Rightarrow \text{rk}(M) = 3.$$

Alternatively $\text{rk}(M) = \# \text{ of leading 1's}$
 $= 3.$

(d) M is not invertible since

- $\text{rk}(M) \neq 4$
- columns don't form a basis
- rows don't form a basis
- RREF \neq Identity

Any of these are good enough answers, by the Fundamental Theorem.

6. First $\exp(x_1, y_1) + (x_2, y_2)$

$$= \exp(x_1 + x_2, y_1 + y_2)$$

$$= (e^{x_1 + x_2}, e^{y_1 + y_2})$$

$$= (e^{x_1} e^{x_2}, e^{y_1} e^{y_2})$$

$$= (e^{x_1}, e^{y_1}) + Q (e^{x_2}, e^{y_2})$$

$$= \exp(x_1, y_1) + Q \exp(x_2, y_2) \quad \checkmark$$

Constants also can come out

$$\exp(\mathcal{L}(x, y)) = \exp(\mathcal{L}x, \mathcal{L}y)$$

$$= (e^{\mathcal{L}x}, e^{\mathcal{L}y})$$

$$= ((e^x)^{\mathcal{L}}, (e^y)^{\mathcal{L}}) = \mathcal{L}(e^x, e^y)$$

$$= \mathcal{L}(\exp(x, y)). \quad \checkmark$$

$$7. (a) \omega_1 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \quad \omega_2 = \begin{pmatrix} -1 \\ 1 \\ 2 \end{pmatrix} \quad \omega_3 = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$$

$$v_1 = \omega_1 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$$

$$v_2 = \omega_2 - \frac{\omega_2 \cdot v_1}{\|v_1\|^2} v_1$$

$$= \begin{pmatrix} -1 \\ 1 \\ 2 \end{pmatrix} - \frac{2}{2} \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}$$

$$v_2 = \begin{pmatrix} -1 \\ 1 \\ 2 \end{pmatrix} - \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 2 \end{pmatrix}$$

$$v_3 = \omega_3 - \frac{\omega_3 \cdot v_1}{\|v_1\|^2} v_1 - \frac{\omega_3 \cdot v_2}{\|v_2\|^2} v_2$$

$$= \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} - \frac{-1}{2} \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} - \frac{2}{4} \begin{pmatrix} 0 \\ 0 \\ 2 \end{pmatrix}$$

$$= \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + \begin{pmatrix} -1/2 \\ 1/2 \\ 0 \end{pmatrix} - \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} -1/2 \\ 1/2 \\ 0 \end{pmatrix}$$

$$v_3 = \begin{pmatrix} 1/2 \\ 1/2 \\ 0 \end{pmatrix}$$

Normalizing we get

$$u_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} \quad u_2 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \quad u_3 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}.$$

(b)

$$\text{Proj}_W v = (v \cdot u_1) u_1 + (v \cdot u_2) u_2 \quad \text{where}$$

u_1, u_2 are an orthonormal basis of W .

From part (a) W has orthonormal basis

$$u_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} \quad \text{and} \quad u_2 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}.$$

$$\begin{aligned} \therefore \text{proj}_W (2, 1, 2) &= \left(\begin{pmatrix} 2 \\ 1 \\ 2 \end{pmatrix} \cdot \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} \right) \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} \\ &\quad + \left(\begin{pmatrix} 2 \\ 1 \\ 2 \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right) \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \\ &= \frac{1}{2} (-1) \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} + 2 \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1/2 \\ -1/2 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \\ 2 \end{pmatrix} \\ &= \begin{pmatrix} 1/2 \\ -1/2 \\ 2 \end{pmatrix}. \end{aligned}$$

8.

$$(a) A = \begin{pmatrix} 0 & 0 & -3 \\ 2 & 2 & -1 \\ 1 & 1 & -2 \end{pmatrix}$$

$$A^2 = \begin{pmatrix} 0 & 0 & -3 \\ 2 & 2 & -1 \\ 1 & 1 & -2 \end{pmatrix} \begin{pmatrix} 0 & 0 & -3 \\ 2 & 2 & -1 \\ 1 & 1 & -2 \end{pmatrix} = \begin{pmatrix} -3 & -3 & 6 \\ 3 & 3 & -6 \\ 0 & 0 & 0 \end{pmatrix}$$

$$A^3 = \begin{pmatrix} 0 & 0 & -3 \\ 2 & 2 & -1 \\ 1 & 1 & -2 \end{pmatrix} \begin{pmatrix} -3 & -3 & 6 \\ 3 & 3 & -6 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

(b) Since $A^3 = 0$, then

$$e^A = I + A + \frac{1}{2}A^2 + 0 + 0 + \dots$$

$$= I + A + \frac{1}{2}A^2$$

$$= \begin{pmatrix} 1 & & \\ & 1 & \\ & & 1 \end{pmatrix} + \begin{pmatrix} 0 & 0 & -3 \\ 2 & 2 & -1 \\ 1 & 1 & -2 \end{pmatrix}$$

$$+ \frac{1}{2} \begin{pmatrix} -3 & -3 & 6 \\ 3 & 3 & -6 \\ 0 & 0 & 0 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 & -3 \\ 2 & 3 & -1 \\ 1 & 1 & -1 \end{pmatrix} + \begin{pmatrix} -3/2 & -3/2 & 3 \\ 3/2 & 3/2 & -3 \\ 0 & 0 & 0 \end{pmatrix}$$

$$= \begin{pmatrix} -1/2 & -3/2 & 0 \\ 7/2 & 9/2 & -4 \\ 1 & 1 & -1 \end{pmatrix}$$

- Alternatively, the longer way is to compute the Jordan form. I had hoped that part (a) was a hint to do it the first way.

$$\det(A - \lambda I) = \det \begin{pmatrix} -\lambda & 0 & -3 \\ 2 & 2-\lambda & -1 \\ 1 & 1 & -2-\lambda \end{pmatrix} = 0$$

$$-\lambda \left((2-\lambda)(-2-\lambda) + 1 \right) + (-3) \left(2 - (2-\lambda) \right) = 0$$

$$-\lambda(-4 + \lambda^2 + 1) + (-3\lambda) = 0$$

$$-\lambda^3 + 3\lambda - 3\lambda = 0$$

$$-\lambda^3 = 0 \implies \lambda = 0, 0, 0$$

$$V_0 = \ker(A) = \ker \begin{pmatrix} 0 & 0 & -3 \\ 2 & 2 & -1 \\ 1 & 1 & -2 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 0 & -3 \\ 2 & 2 & -1 \\ 1 & 1 & -2 \end{pmatrix} \xrightarrow{\text{Swap } r_1, r_3} \begin{pmatrix} 1 & 1 & -2 \\ 2 & 2 & -1 \\ 0 & 0 & -3 \end{pmatrix}$$

$$\xrightarrow{-2r_1 + r_2} \begin{pmatrix} 1 & 1 & -2 \\ 0 & 0 & 3 \\ 0 & 0 & -3 \end{pmatrix}$$

$$\xrightarrow{+r_2 + r_3} \begin{pmatrix} 1 & 1 & -2 \\ 0 & 0 & 3 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\xrightarrow{2/3 r_2 + r_1} \begin{pmatrix} 1 & 1 & 0 \\ 0 & 0 & 3 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\xrightarrow{1/3 r_2} \begin{pmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\text{So } V_0 = \ker(A) = \begin{pmatrix} -y \\ y \\ 0 \end{pmatrix} = \text{span} \left(\begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} \right)$$

So Jordan chain is $w_1 = \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}, w_2, w_3,$

$$Aw_2 = w_1 \quad \text{and} \quad Aw_3 = w_2.$$

$$\begin{pmatrix} 0 & 0 & -3 \\ 2 & 2 & -1 \\ 1 & 1 & -2 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} \xrightarrow{\text{swap}} \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix} \xrightarrow{-2r_1+r_2} \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix} \xrightarrow{r_1+r_2} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

$$\xrightarrow{2/3r_2+r_1} \begin{pmatrix} 2/3 \\ 1 \\ 0 \end{pmatrix} \xrightarrow{1/3r_2} \begin{pmatrix} 2/3 \\ 1/3 \\ 0 \end{pmatrix}$$

$$\left(\begin{array}{ccc|c} 1 & 1 & 0 & 2/3 \\ 0 & 0 & 1 & 1/3 \\ 0 & 0 & 0 & 0 \end{array} \right) \rightarrow \begin{cases} x = -y + 2/3 \\ z = 1/3 \end{cases}$$

$$\text{So } w_2 = \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -y + 2/3 \\ y \\ 1/3 \end{pmatrix} = \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} y + \begin{pmatrix} 2/3 \\ 0 \\ 1/3 \end{pmatrix}$$

$$\Rightarrow w_2 = \begin{pmatrix} 2/3 \\ 0 \\ 1/3 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 0 & -3 \\ 2 & 2 & -1 \\ 1 & 1 & -2 \end{pmatrix} w_3 = \begin{pmatrix} 2/3 \\ 0 \\ 1/3 \end{pmatrix}$$

$$\begin{pmatrix} 2/3 \\ 0 \\ 1/3 \end{pmatrix} \rightarrow \begin{pmatrix} 1/3 \\ 0 \\ 2/3 \end{pmatrix} \rightarrow \begin{pmatrix} 1/3 \\ -2/3 \\ 2/3 \end{pmatrix} \rightarrow \begin{pmatrix} 1/3 \\ -2/3 \\ 0 \end{pmatrix}$$

$$\rightarrow \begin{pmatrix} -1/9 \\ -2/3 \\ 0 \end{pmatrix} \rightarrow \begin{pmatrix} -1/9 \\ -2/9 \\ 0 \end{pmatrix}$$

$$\left(\begin{array}{ccc|c} 1 & 1 & 0 & -1/9 \\ 0 & 0 & 1 & -2/9 \\ 0 & 0 & 0 & 0 \end{array} \right) \quad \begin{cases} x = -y - 1/9 \\ z = -2/9 \end{cases}$$

$$w_3 = \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -y - 1/9 \\ y \\ -2/9 \end{pmatrix} = \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} y + \begin{pmatrix} -1/9 \\ 0 \\ -2/9 \end{pmatrix}$$

$$\text{So } \omega_3 = \begin{pmatrix} -1/9 \\ 0 \\ -2/9 \end{pmatrix}.$$

Thus

$$\begin{pmatrix} 0 & 0 & -3 \\ 2 & 2 & -1 \\ 1 & 1 & -2 \end{pmatrix} = \begin{pmatrix} -1 & 2/3 & -1/9 \\ 1 & 0 & 0 \\ 0 & 1/3 & -2/9 \end{pmatrix} \begin{pmatrix} 0 & 1 & \\ & 0 & 1 \\ & & 0 \end{pmatrix} \begin{pmatrix} -1 & 2/3 & -1/9 \\ 1 & 0 & 0 \\ 0 & 1/3 & -2/9 \end{pmatrix}^{-1}$$

$$\text{So } e^{\begin{pmatrix} 0 & 0 & -3 \\ 2 & 2 & -1 \\ 1 & 1 & -2 \end{pmatrix}} = \begin{pmatrix} -1 & 2/3 & -1/9 \\ 1 & 0 & 0 \\ 0 & 1/3 & -2/9 \end{pmatrix} e^{\begin{pmatrix} 0 & 1 & \\ & 0 & 1 \\ & & 0 \end{pmatrix}} \begin{pmatrix} -1 & 2/3 & -1/9 \\ 1 & 0 & 0 \\ 0 & 1/3 & -2/9 \end{pmatrix}^{-1}$$

$$e^{\begin{pmatrix} 0 & 1 & \\ & 0 & 1 \\ & & 0 \end{pmatrix}} = I + N + \frac{1}{2} N^2$$

$$= \begin{pmatrix} 1 & & \\ & 1 & \\ & & 1 \end{pmatrix} + \begin{pmatrix} 0 & 1 & \\ & 0 & 1 \\ & & 0 \end{pmatrix} + \frac{1}{2} \begin{pmatrix} 0 & 0 & 1 \\ & 0 & 0 \\ & & 0 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 1 & \frac{1}{2} \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\Rightarrow e^A = \begin{pmatrix} -1 & 2/3 & -1/9 \\ 1 & 0 & 0 \\ 0 & 1/3 & -2/9 \end{pmatrix} \begin{pmatrix} 1 & 1 & 1/2 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 \\ 2 & 2 & -1 \\ 3 & 3 & 6 \end{pmatrix}$$

$$= \begin{pmatrix} -1/2 & -3/2 & 0 \\ 7/2 & 9/2 & -4 \\ 1 & 1 & -1 \end{pmatrix}$$

Anyway don't
do it this
way if you
can avoid it!

9.

(a). Let $\Lambda = \begin{pmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \lambda_3 \end{pmatrix}$.

Then

$$P_A(\Lambda) = c_3 \begin{pmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \lambda_3 \end{pmatrix}^3 + c_2 \begin{pmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \lambda_3 \end{pmatrix}^2 + c_1 \begin{pmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \lambda_3 \end{pmatrix} + c_0 \begin{pmatrix} 1 & & \\ & 1 & \\ & & 1 \end{pmatrix}$$

$$= c_3 \begin{pmatrix} \lambda_1^3 & & \\ & \lambda_2^3 & \\ & & \lambda_3^3 \end{pmatrix} + c_2 \begin{pmatrix} \lambda_1^2 & & \\ & \lambda_2^2 & \\ & & \lambda_3^2 \end{pmatrix}$$

$$+ c_1 \begin{pmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \lambda_3 \end{pmatrix} + c_0 \begin{pmatrix} 1 & & \\ & 1 & \\ & & 1 \end{pmatrix}$$

$$= \begin{pmatrix} c_3 \lambda_1^3 + c_2 \lambda_1^2 + c_1 \lambda_1 + c_0 & & \\ & c_3 \lambda_2^3 + c_2 \lambda_2^2 + c_1 \lambda_2 + c_0 & \\ & & \dots \end{pmatrix}$$

Since λ_i are roots of the char poly then

$$c_3 \lambda_i^3 + c_2 \lambda_i^2 + c_1 \lambda_i + c_0 = 0$$

Each of the above diagonal entries is 0, so

$$\Rightarrow P_A(\Lambda) = 0 \quad \square$$

(b). By the decomposition

$$A = S \Lambda S^{-1} \quad \text{so}$$

$$P_A(A) = c_3 (S \Lambda S^{-1})^3 + c_2 (S \Lambda S^{-1})^2 + c_1 (S \Lambda S^{-1}) + c_0 I$$

$$= c_3 S \Lambda^3 S^{-1} + c_2 S \Lambda^2 S^{-1} + c_1 S \Lambda S^{-1} + c_0 S I S^{-1}$$

$$= S \left(c_3 \Lambda^3 + c_2 \Lambda^2 + c_1 \Lambda + c_0 I \right) S^{-1}$$

$$= S P_A(\Lambda) S^{-1} = S O S^{-1} = O$$

All in all $P_A(A) = O.$

□