Homework 2 Solutions February 1, 2020

**5.11.1**. Determine whether a bunch of matrices are symmetric, skew-symmetric, Hermitian, or skew-Hermitian.

Solution. a. symmetric b. skew-Hermitian c. Hermitian d. skew-symmetric

**5.11.2**. a. Verify that the  $2 \times 2$  rotation matrix is an orthogonal matrix. b. Prove that it actually rotates vectors by  $\theta$ .

Solution. a. This follows from  $\sin^2 + \cos^2 = 1$ . b. This follows from  $\sin(a+b) = \sin(a)\cos(b) + \cos(a)\sin(b)$  and  $\cos(a+b) = \cos(a)\cos(b) - \sin(a)\sin(b)$ .

**5.11.3**. Show that a bunch of matrices do certain things the textbook is claiming.

Solution. a. A(x, y, z) = (x, y, -z) which is the opposite side of the xy-plane. b. A(x, y, z) = (x, -y, -z) which is on the opposite side of the x axis.

c. A(x, y, z) = (-x, -y, -z) which is on the opposite side of the origin.

d. This one keeps the same x but rotates y and z, which means you're rotating around the x axis. Also note that (1,0,0) is an eigenvector with eigenvalue 1. e. You multiply (b) and (d).

**5.11.4.** a. If a  $2 \times 2$  matrix A is proper, show that it is a rotation matrix for some  $\theta$ . b. Show that two matrices are not proper, and find all nonproper  $2 \times 2$  matrices.

Solution. a. If  $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$  is an orthogonal matrix, then (a, b) and (c, d) are orthogonal unit vectors by the  $AA^T = I$  criterion. Thus  $(c, d) = \pm(-b, a)$ . If det A = 1, this restricts (c, d) = (-b, a). Since (a, b) is a unit vector, then it is on the unit circle and has the form  $(\cos(\theta), \sin(\theta))$ . Therefore A is a rotation matrix.

b. The two matrices are improper since they are orthogonal with determinant -1. By the above argument, we can see all improper  $2 \times 2$  matrices are of the form  $\begin{bmatrix} a & b \\ b & -a \end{bmatrix}$ , namely a rotation matrix followed by a reflection.

5.11.6, 5.11.7. Diagonalize some matrices.

Solution. 6. 
$$D = \begin{bmatrix} -2i & 0 \\ 0 & 2i \end{bmatrix}, C = \frac{1}{\sqrt{2}} \begin{bmatrix} -i & i \\ 1 & 1 \end{bmatrix}$$
  
7.  $D = \begin{bmatrix} -4 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 3 \end{bmatrix} C = \begin{bmatrix} v_1 & v_2 & v_3 \end{bmatrix}$  where  $v_1 = \frac{1}{\sqrt{35}}(-3, 5, 1), v_2 = \frac{1}{\sqrt{10}}(1, 0, 3)$ , and  $v_3 = \frac{1}{\sqrt{14}}(-3, -2, 1)$ .

**5.11.13**. If A is a real skew-symmetric matrix, prove that I - A and I + A are nonsingular and that  $(I - A)(I + A)^{-1}$  is orthogonal.

Solution. Since A is real skew-symmetric, then it has only real eigenvalue  $\lambda = 0$  if any. Then  $\lambda = \pm 1$  are not eigenvalues, so by definition  $A \pm I$  is nonsingular. Now we show that  $B = (I - A)(I + A)^{-1}$  is orthogonal by showing  $B^T = B^{-1}$ .

This is true since

$$B^{T} = (I - A^{T})(I + A^{T})^{-1} = (I + A)(I - A)^{-1} = B^{-1}.$$

**5.15.1, 5.15.5.** For each of the following quadratic forms, find a symmetric matrix A for it, find the eigenvalues of A, find an orthonormal set of eigenvectors, and an orthogonal diagonalizing matrix.

1. 
$$4x_1 + 4x_1x_2 + x_2^2$$
  
5.  $x_1^2 + x_1x_2 + x_1x_3 + x_2x_3$   
Solution. 1.  $A = \begin{bmatrix} 4 & 2 \\ 2 & 1 \end{bmatrix}$  with eigenvalues  $\lambda = 0, 5$  and orthogonal eigenbasis  
 $\frac{1}{\sqrt{5}}(-1,2)$  and  $\frac{1}{\sqrt{5}}(2,1)$ .  
5.  $A = \frac{1}{2} \begin{bmatrix} 2 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix}$  with eigenvalues  $\lambda = -1/2, 0, 3/2$  and eigenbasis  $\frac{1}{\sqrt{2}}(0, -1, 1)$   
 $\frac{1}{\sqrt{3}}(-1, 1, 1)$ , and  $\frac{1}{\sqrt{6}}(2, 1, 1)$ .  
5.15.8, 5.15.9. Make a sketch of the following conic sections.  
8.  $y^2 - 2xy + 2x^2 - 5 = 0$   
9.  $y^2 - 2xy + 5x = 0$ 

Solution. You find the eigenbasis, change the variables, then sketch whether you get a rotated parabola, ellipse, or circle, hyperbola, or two lines. Did you know that a parabola is just an ellipse with one end at infinity?

8. rotated ellipse

9. rotated hyperbola

**5.20.1a**. Let  $T: V \to V$  be the transformation given by T(x) = cx for some fixed scalar c. Prove that T is unitary iff |c| = 1.

Solution. If T is unitary and has an eigenvalue  $\lambda$  then  $|\lambda| = 1$  by theorem 5.16. For T(x) = cx, c is an eigenvalue trivially, so that |c| = 1.

**5.20.1b**. If V is one-dimensional, prove that only unitary transformation on V are those described in (a). If V is real, then  $c = \pm 1$ .

Solution. Since V is one-dimensional, then it has a basis element e, and therefore T(e) = ce for some scalar c. Since e is a basis T(x) = cx for all  $x \in V$ . Therefore (a) applies that if T is unitary then |c| = 1. If the underyling field is  $\mathbb{R}$ , then the only scalars with magnitude one are  $c = \pm 1$ . **5.20.2.** Prove the following statements about a real orthogonal  $n \times n$  matrix A. (a) If  $\lambda$  is a real eigenvalue of A, then  $\lambda = \pm 1$ . (b) If  $\lambda$  is a complex eigenvalue of A, then the complex conjugate  $\overline{\lambda}$  is also an eigenvalue of A. (c) If n is odd, then A has at least one real eigenvalue.

Solution. (a) Again by theorem 5.16, then any eigenvalue of an orthogonal matrix has magnitude 1. The only scalars in  $\mathbb{R}$  with that property are  $\pm 1$ . (b) Since A is a real matrix and all complex roots of real polynomials come in conjugate pairs, this claim follows easily. (c) If n is odd, then the characteristic polynomial is off odd degree. All odd degree real polynomials have at least one real solution by the intermediate value theorem.

**5.20.3**. Let V be a real Euclidean space of dimension n. An orthogonal transformation  $T: V \to V$  with determinent 1 is called a rotation. If n is odd, prove that 1 is an eigenvalue for T.

Solution. Since V is odd dimensional, then T has at least one real eigenvalue  $\lambda$ . Since T is orthogonal, then we know that  $|\lambda| = 1$ , so that  $\lambda = \pm 1$ . Since the complex eigenvalue come in conjugate pairs, then there are an odd number of real eigenvalues. Since det A = 1, then -1 can only be a real eigenvalue an even number of times. Since even numbers are not odd numbers, there must be a left over real eigenvalue not equal to -1, so therefore  $\lambda = 1$  is an eigenvalue.

**1a.** For any square matrix, show that  $A + A^T$  is symmetric and  $A - A^T$  is skew symmetric.

Solution. Note that

$$(A + A^T)^T = A^T + A^{T^T} = A^T + A.$$

For the skew-symmetric case

$$(A - A^T)^T = A^T - A = -(A - A^T).$$

**1b.** Show that any square matrix can be expressed uniquely as a sum of one symmetric and one skew-symmetric matrix.

Solution. We have at least one such decomposition by 1a since

$$A = \frac{1}{2}(A + A^{T}) + \frac{1}{2}(A - A^{T}).$$

To show that this decomposition is unique, assume A = B + C = B' + C' where B, B' are symmetric and C, C' are skew-symmetric. Then B + C = B' + C' and thus (B - B') + (C - C') = 0. Note that B - B' and C - C' are symmetric and

skew-symmetric respectively. Thus if we can show the 0 matrix has a unique decomposition, then B - B' = 0 and C - C' = 0 and the proof will be done.

Now let B + C = 0 be such a decomposition of the 0 matrix. Taking the transpose, we obtain that B - C = 0 as well. Adding the equations yields 2B = 0 so that B = 0 and therefore C = 0. Thus 0 has a unique decomposition, and by the above argument so does any general A.

**1c.** Show that if n is odd, then any  $n \times n$  skew-symmetric matrix has determinent 0.

Solution. Recall that any real eigenvalue of a skew-symmetric matrix must be 0. If n is odd, then the matrix A has at least one real eigenvalue. Since det  $A = \prod_i \lambda_i$ , and at least one  $\lambda_i = 0$ , then det A = 0.

1d. Show that any nonzero  $3 \times 3$  skew-symmetric matrix has rank exactly 2.

Solution. This argument can be completed by writing out a  $3 \times 3$  matrix and explicitly examining the entries. Consider any skew-symmetric  $3 \times 3$  matrix

$$A = \begin{bmatrix} 0 & a & b \\ -a & 0 & c \\ -b & -c & 0 \end{bmatrix}.$$

Since 3 is odd, then the previous problem implies that  $\det A = 0$  so that  $\operatorname{rk}(A) < 3$ . Since  $A \neq 0$ , then one of a, b, c is not 0. Now we can examine each case.

If  $a \neq 0$ , then the first and second columns are nonzero and independent, so the rank is 2.

If  $b \neq 0$ , then the first and third columns are nonzero and independent, so the rank is 2.

If  $c \neq 0$ , then the second and third columns are nonzero and independent, so the rank is 2.